



Current PNT System/Sensor Challenges

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Before GNSS(GPS)

- **Positioning and Timing were huge problems**
 - We had many different systems working on different principles, different equipment
LORAN, TACAN, VOR, DME, TERCOM, ...
 - Had OK performance locally – short distances
(200 m was excellent result for most applications)
 - In long distances we had to rely on Inertial Navigation which is very expensive, big, power hungry and under strict control (MTCR)
 - Even if you paid all that cost for INS the errors increased by t^2 and t^3

Then GPS (GNSS) came

- You can get position less than 5 m (< 1m if you have WAAS)
- You can get timing < 1 μ sec (< 15 ns if you have military signal)
- Can be a few dollars (Your phone has more than one system)
- If you have some basic maps you can use them for navigation
- Available in almost all of earth (Except caves, indoor, valleys)
- Basicly unbelievable performance to almost no cost to user
- Ended up being used everywhere – **intended or not**

Some Use Areas

- Military and civilian Navigation (Positioning and Guidance to target)
- Time synchronization of military communication equipment
- Time synchronization of Banking system (Transfers, ATM's etc)
- Precision Farming (Knew exactly where each crop is and ...)
- Air Traffic Control (ADS-B)
- Autonomous Driving
- UAV Flying (Autonomous or not)
- Rail System optimization
- Freeway average speed calculation / speed tickets

WE RELY ON GPS ON EVERY ASPECT OF OUR EVERY DAY LIVES.

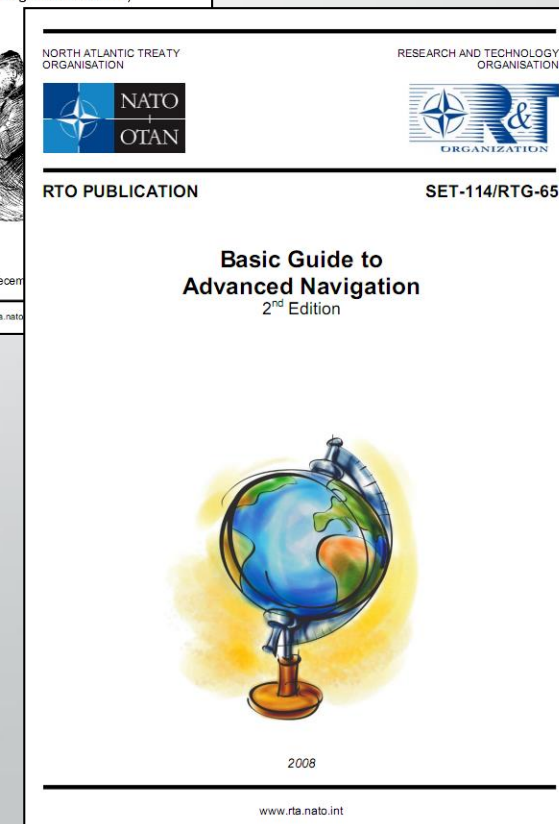
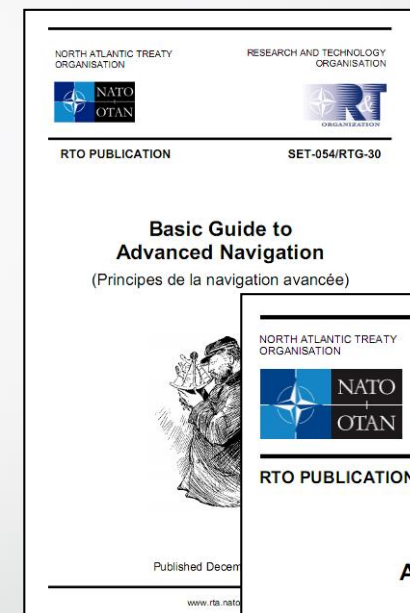
GNSS is the trend Now!



	First Launch	Operational	Status (Now)
GPS	1978	1993	31 of 24+3
GLONASS	1982	1993 – 1995 - 2010	27 of 24
BEIDEU	30/10/2000	2020	3+3+24
GALILEO	28/12/2005	2016	22 of 30 satel.
IRNSS	1/7/2013	Regional	3+5
QZSS	11/9/2010	Augmentation	1+3

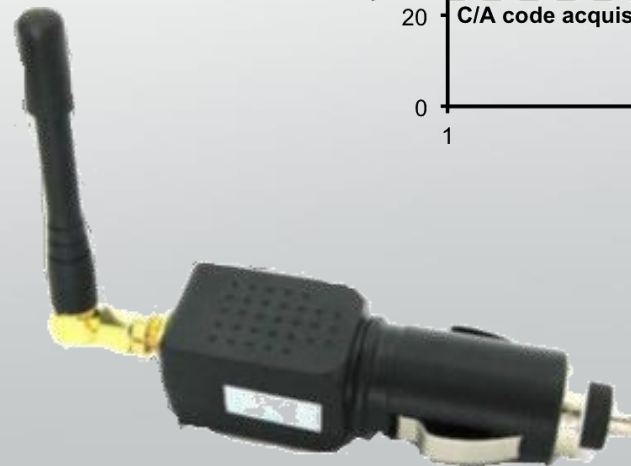
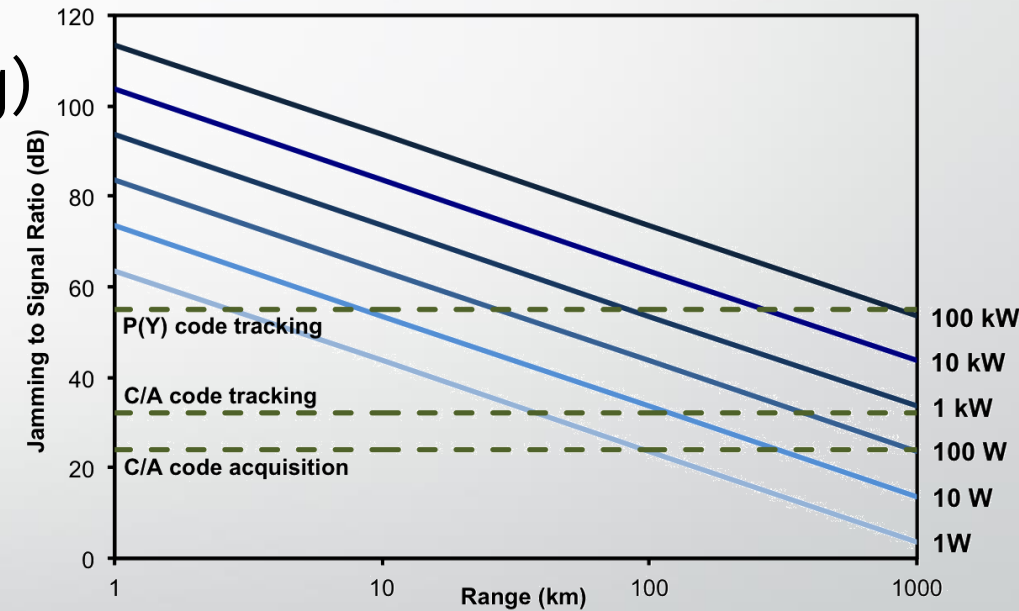
NATO Navigation Booklets

- We prepared 3 NATO Booklets over the years
 - Basic Guide to Advanced Navigation
 - INS, GPS, INS/GPS and Technology Trends
 - Basic Guide to Advanced Navigation 2nd Ed.
 - Dead Reckoning Navigation Systems
 - Map Matching Navigation Systems
 - Externally Dependent Navigation Systems
 - Navigation Sensors and Systems in GNSS Degraded and Denied Environments
 - GNSS Vulnerabilities
 - Scenarios and effect of GNSS jamming, spoofing
 - Possible technological solutions



What's the problem?

- But GNSS (GPS) can be stopped – Way too easily
 - Interference (unintended jamming)
 - Jamming
 - Spoofing
 - Space weather
 - Space attack
 - Cyber Attack



CHALLENGES

PROTECT GNSS (GPS)

- Antijam antennas
- Improvements (M-code)

INDEPENDENT TIMING

- Chip Scale Atomic Clock

Alternate Nav Systems

INS

e-Loran

UWB

TACAN / VOR+DME

Map Matching

Visual Navigation

Pulsar Navigation

Doppler Based Navigation

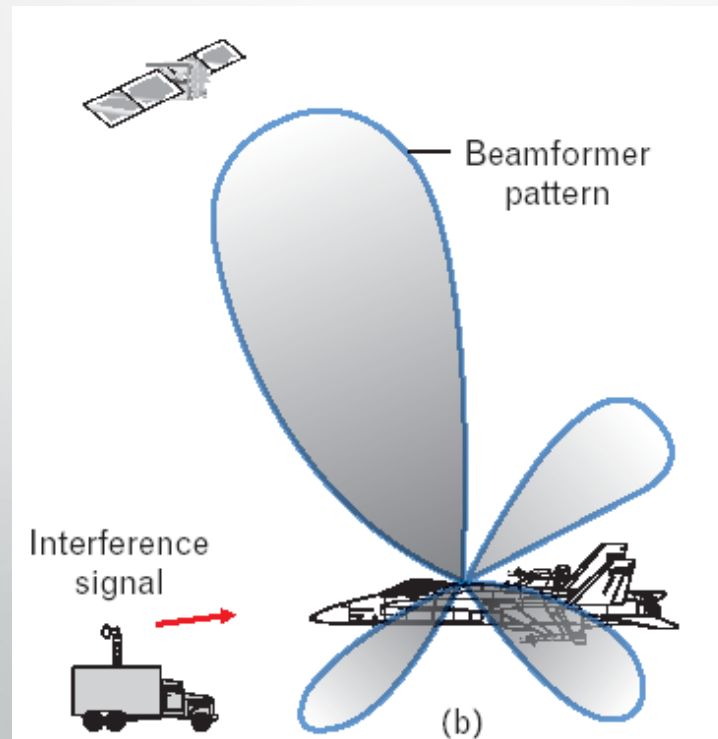
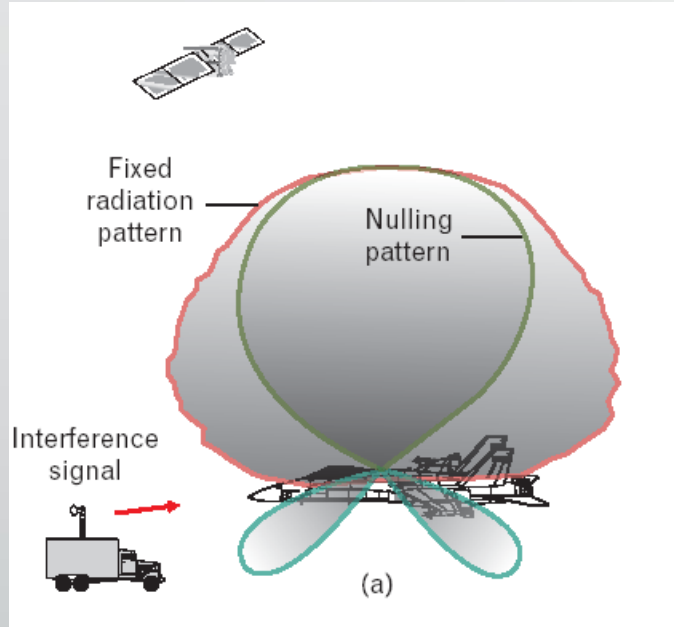
STARLINK

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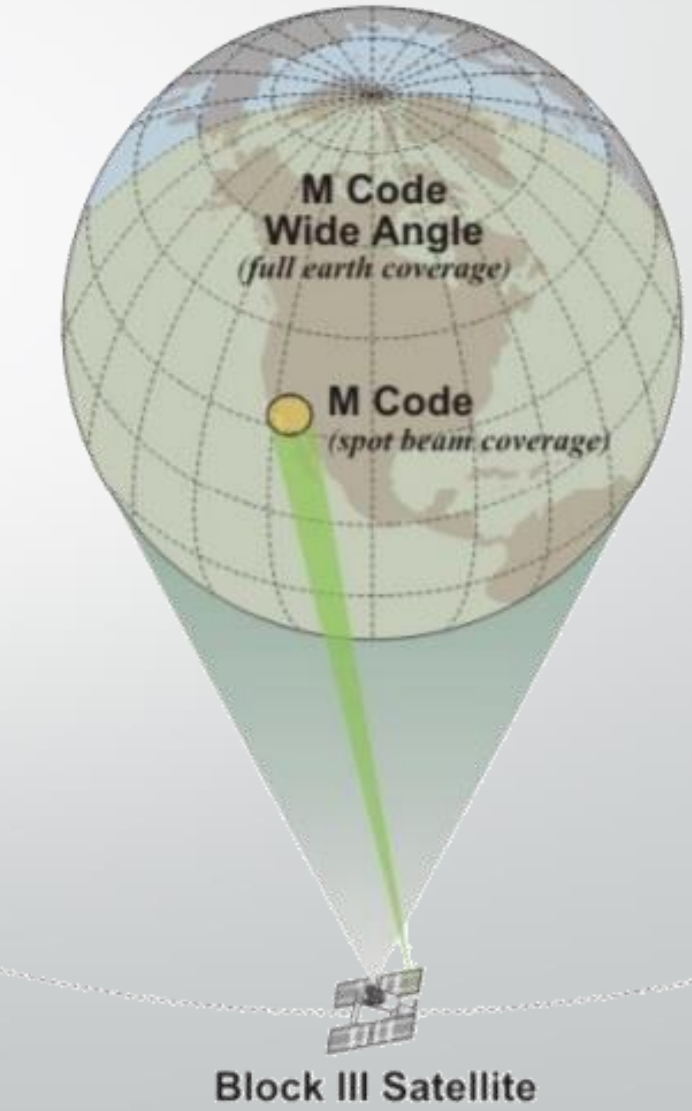
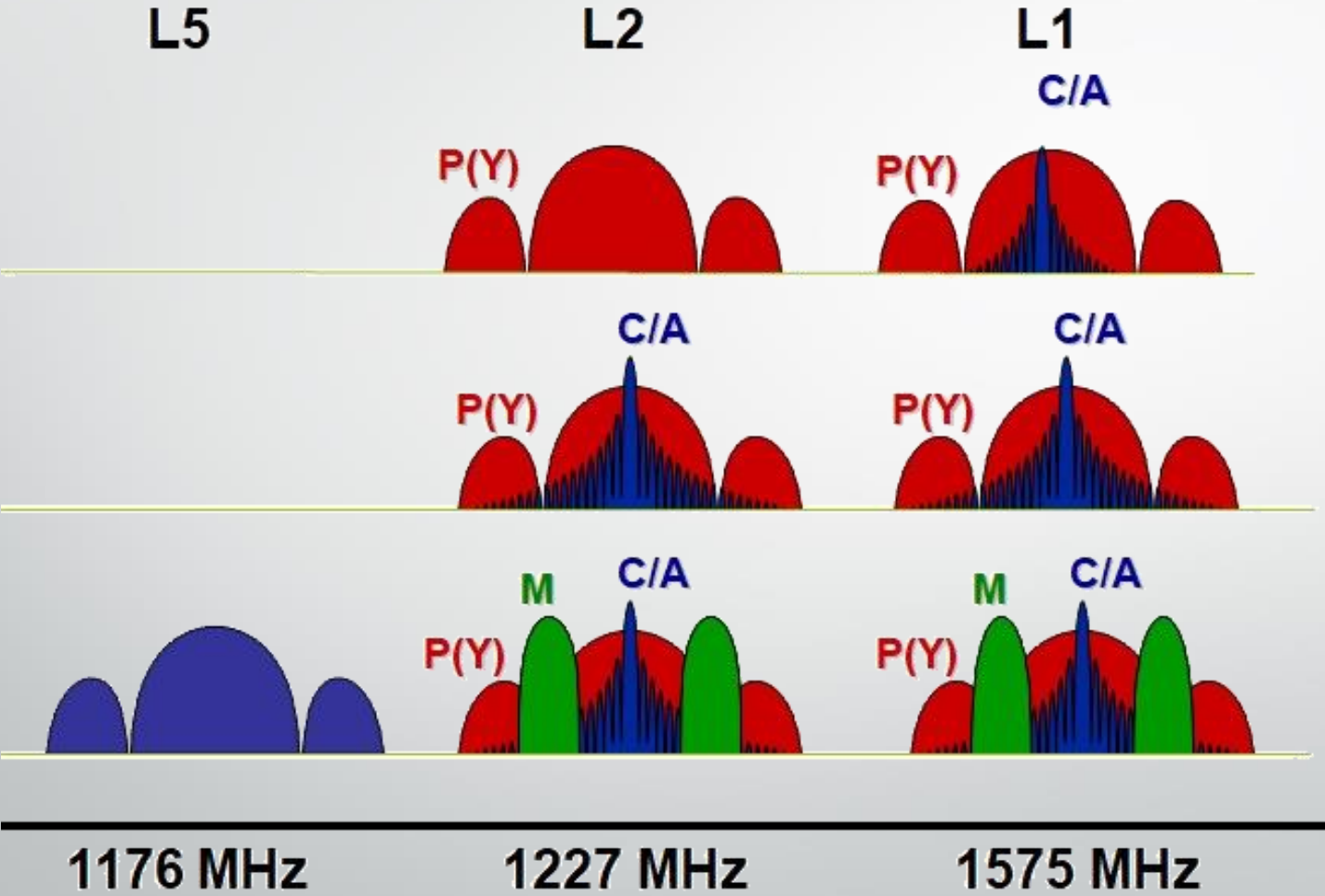
Integrated Navigation Systems

Anti Jam - CRPA Antenna

- Use Multi antenna systems to get
 - Directional capability
 - Nulling



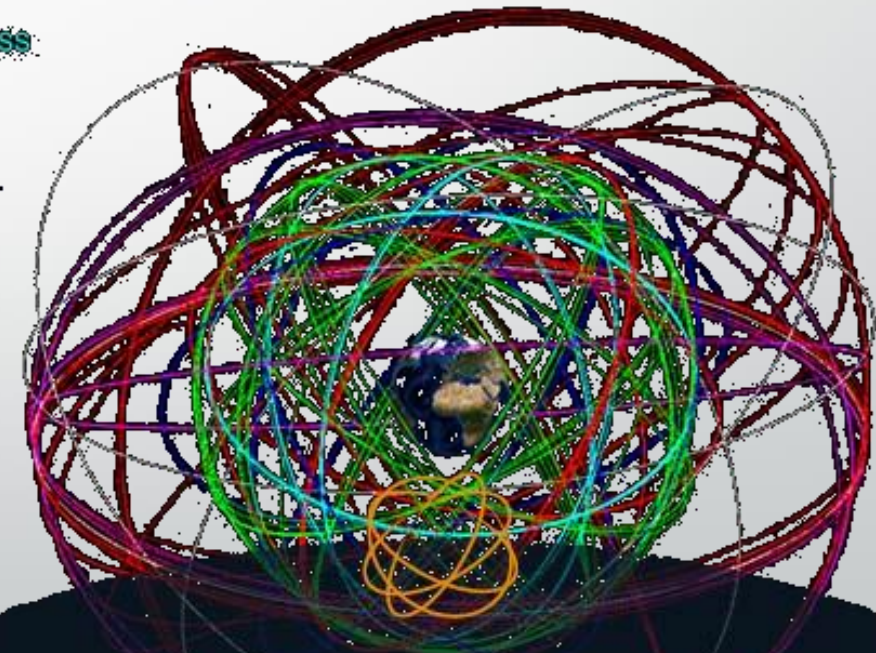
GPS/GNSS Modernization



Multi Constellation

- Once there were only GPS and we were worried about seeing at least 4 satellites
- Now There Are
 - GPS - 31
 - GALILEO - 22
 - BEIDOU - 30
 - GLONASS - 27
 - + Others
- Why not use all available
- Such commercial system are now available

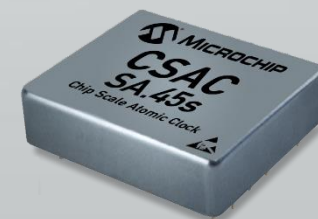
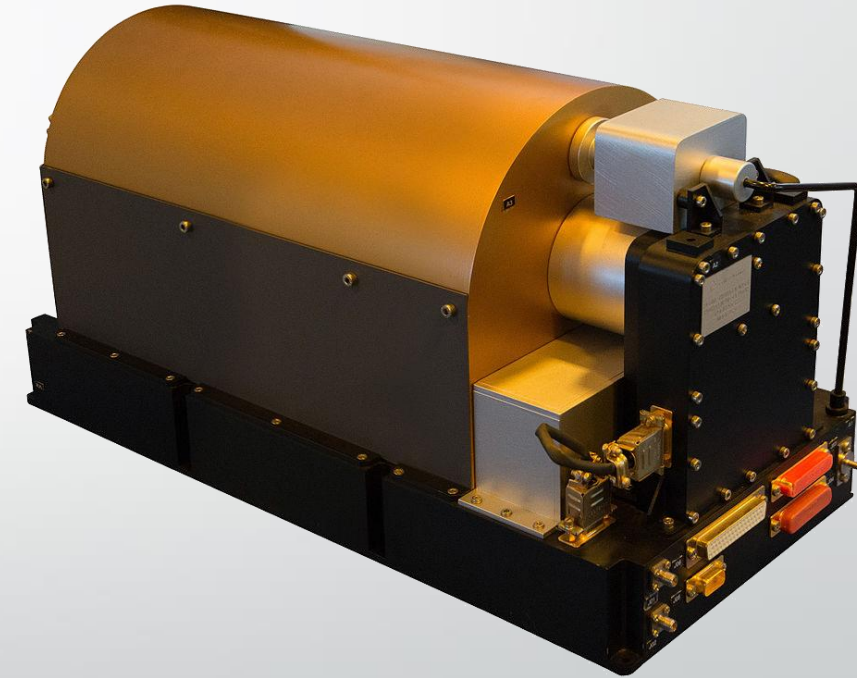
GPS
GLONASS
Galileo
Beidou
QZSS
IRNSS



MULTI-GNSS

Independent Time Source

- If GPS is jammed timing will also be lost
 - Crypto technology
 - Bank Systems
 - Average Speed calc.
- Need independent time
 - Atomic Clocks are big and expensive
 - Chip scale atomic clock



Military Code vs. Multi Constellation

- If you don't own your own GNSS System then :
 - Should you use Country X's military receivers
 - Better performance under jamming
 - Very hard to spoof
 - Reliance on country X
 - Or Should you use all GNSS systems but civil signals
 - More than enough free signals
 - Easier to jam and Spoof
 - Commercial / Cheap Solutions readily available
 - Or Should you start your own GNSS

Anti UAV vs. Anti Jam

- UAV

- Many different sizes, shapes etc.
- Now they can also be armed
- Are they friendly or are they a threat
- Most of them rely on GNSS for navigation
- Jamming GNSS is one of the ways to stop UAV attacks



- It will also effect your own systems
- Will effect civilian systems, air traffic
- Not easy to find, eliminate jammers in real World.



Integrated Navigation Systems

- Which ones to Integrate
 - Legacy but still operational systems
 - Inertial Navigation Systems (Still expensive and Heavy)
 - For which user – Air, Land, Sea or Space
 - How many different versions is enough
- How to integrate
 - INS/GPS – you know how use Kalman Filter, error covariances
 - Legacy systems – No error covariances, not aware that there are other systems out there
 - Newly developed – Still most thinks he is the king

Is there a better way of doing things?

- How many times I (We) have to do the same job
 - INS / GPS
 - INS / GNSS
 - INS / Doppler Radar
 - INS / Speed Sensor (Tachometer, Log speed etc.)
 - IMU / UWB
 - IMU / Vision Based
 - IMU / Radar
- Then restart using 3 at a time then 4 at a time etc.

SET 309 - PNT Open System Architecture

- Can we create a standard architecture where each navigation system provides data ready to be integrated by other systems
 - Position, Attitude
 - Timing
 - Error covariances
 - Others
- So that any navigation system can automatically be integrated by an integration algorithm
 - Several separate navigation systems
 - A hardware to integrate
 - An algorithm to integrate

PLUG AND PLUG INTEGRATED NAVIGATION SYSTEM